# Directed Topology and Concurrency

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Geometric Semantics	Combinatorial Model	Invariants	Conclusion
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#### Algebraic View

A program is a sequence of instructions

• plus branches and loops

Kleene algebra:

- set *S* with operations:
- concatenation  $\otimes$
- choice  $\oplus$
- repetition \*
- idempotent semiring with unary \* which computes fixed points



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Geometric View			

A program is a sequence of instructions

• ignoring branches and loops for now





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Geometric View			

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#### Holes

#### Adding mutual exclusion:



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#### Adding mutual exclusion:



• homotopic paths  $\hat{=}$  equivalent executions

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## Summing Up



- A program is a topological space
- An execution is a path through said space
- Two executions are equivalent iff their paths are homotopic

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# Summing Up



- A program is a directed topological space
- An execution is a directed path through said space
- Two executions are equivalent iff their dipaths are dihomotopic

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Directed Spaces			

# Definition (po-space)

A partially ordered space is a topological space X together with a partial order  $\leq$  on X such that  $\leq \subseteq X \times X$  is *closed* in the product topology. A morphism of po-spaces is a  $\leq$ -preserving continuous function.

- directed intervals; directed squares, cubes, etc.
- concatenation  $\otimes$ , branching  $\oplus$
- no loops



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Directed Spaces			

# Definition (lpo-space)

A locally partially ordered space is a Hausdorff topological space X together with a relation  $\leq$  on X in which any  $x \in X$  has an open neighborhood  $U \ni x$  such that the restriction of  $\leq$  to U is a closed partial order.

A morphism of po-spaces is a continuous function which is *locally*  $\leq$ -preserving.





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#### Directed Spaces

#### Definition (d-space)

A directed space is a topological space X together with a set  $\vec{P}X$  of directed paths  $I \rightarrow X$  such that

- all constant paths are directed,
- concatenations of directed paths are directed, and
- reparametrizations and restrictions of directed paths are directed.

A morphism of d-spaces is a continuous function which preserves directed paths.

- po-spaces  $\hookrightarrow$  lpo-spaces  $\hookrightarrow$  d-spaces (not full)
- po-spaces are *loop-free*; lpo-spaces are *vortex-free*
- d-spaces are nice: axiomatize directly our objects of interest (dipaths); have good categorical properties

Directed Daths	nd Homotopics		
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#### Directed Paths and Homotopies

• the directed interval  $\vec{l}$ :

- $([0,1], \leq)$  (usual order): po-space; lpo-space •  $([0,1], \vec{P}[0,1])$ : all (weakly) increasing paths
- dipaths in X: morphisms I → X
  for d-space (X, PX): dipaths = PX
- a dihomotopy  $H: I \times \vec{l} \to X$ :
  - all  $H(s, \cdot)$  dipaths
  - $H: I \times I \to X$  continuous
  - $H(\cdot,0)$  and  $H(\cdot,1)$  constrained
  - (some variants exist)

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Summing IIn	Amain		

# Summing Up, Again



- A program is a directed topological space
  - po-space, lpo-space, d-space
  - (other models exist)
- An execution is a directed path through said space
- Two executions are equivalent iff their dipaths are dihomotopic

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# Combinatorial Model

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Transition Sys	stems?		



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Transition System	ms?		

Programs are transition systems!



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Transition Syst	ems?		

Programs are transition systems!

have lost info on "forbidden squares"



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Transition	Svstems?		

Programs are transition systems!

- have lost info on "forbidden squares"
- Higher-dimensional automata:
  - transition systems
  - plus info on concurrency



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Transition Syst	ems?		

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#### Higher-Dimensional Automata

#### Definition (pc-set)

A precubical set is a graded set  $X = \{X_n\}_{n \ge 0}$  together with face maps  $\delta_i^0, \delta_i^1 : X_n \to X_{n-1}$ , for i = 1, ..., n, satisfying  $\delta_i^{\nu} \delta_j^{\mu} = \delta_{j-1}^{\mu} \delta_i^{\nu}$  for i < j.



#### Definition (HDA)

A higher-dimensional automaton is a pc-set X together with a labeling  $\lambda: X_1 \to \Sigma$  and specified start and accept cells  $I, F \subseteq X$ .

also need 
$$\lambda(\delta_i^0 x) = \lambda(\delta_i^1 x)$$
 for all  $x \in X_2$   
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first *a*, then *b*; all in parallel with *c*:  $ab \parallel c$ 

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### Examples



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Examples			



 $a \parallel (bc)^*$ 

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#### Geometric Realization

#### Definition

The geometric realization of a pc-set X is the d-space  $|X| = \bigsqcup_{n \ge 0} X_n \times \vec{l^n} / \sim$ , where  $\sim$  is the equivalence generated by  $(\delta_i^{\nu} x, (t_1, \ldots, t_{n-1})) \sim (x, (t_1, \ldots, t_{i-1}, \nu, t_{i+1}, \ldots, t_{n-1})).$ 

- usual coend definition; left adjoint to *singular pc-set* functor
- actually, |X| is an *lpo-space*

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Dipaths in Geom	netric Realizations		



Let  $p : \vec{l} \to |X|$  be a dipath in the geometric realization of pc-set X. • let  $C_p = \{x \in X \mid im(p) \cap |x| \neq \emptyset\}$  – all cells touched by p • organize  $C_p$  into a sequence  $c_p = (x_1, \dots, x_m)$  s.t.  $\forall i$ :

$$x_i = \delta^0_+ x_{i+1}$$
 or  $x_{i+1} = \delta^1_+ x_i$  (iterated face maps)

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Dipaths in Geo	metric Realizations		



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 $x_i = \delta^0_+ x_{i+1}$  or  $x_{i+1} = \delta^1_+ x_i$  (iterated face maps)  $\Rightarrow$  the track of p

- any track c gives rise to dipath  $p_c$  (non-unique) with  $c_{p_c} = c$
- if  $c_p = c_q$ , then p and q are dihomotopic

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Homotopy of <sup>-</sup>	Fracks		





• generated by local replacements

- dipaths p, q are dihomotopic iff  $c_p$  and  $c_q$  are homotopic
- tracks c, d are homotopic iff  $p_c$  and  $p_d$  are dihomotopic

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# Summing Up



- precubical sets / higher-dimensional automata: combinatorial models of directed spaces
- natural extension of transition systems; also used in computer science
- closely linked to directed spaces via geometric realization:
  - dipaths  $\hat{=}$  tracks  $\hat{=}$  executions
  - dihomotopy  $\hat{=}$  track homotopy  $\hat{=}$  equivalence of executions
| Geometric Semantics | Combinatorial Model | Invariants | Conclusion |
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# Invariants

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Fundamental Cat	egory		

- topological space  $X \rightsquigarrow$  fundamental group  $\pi(X)$ 
  - all information may be reduced to loops (and base points)
- directed spaces: no reduction to loops!
- $\Rightarrow$  directed space  $X \rightsquigarrow$  fundamental category  $\vec{\Pi}X$ 
  - objects points of X
  - morphisms dihomotopy classes of dipaths
  - inspired by fundamental groupoids of topological spaces
  - (higher dihomotopy invariants: unclear!)









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### Path Spaces

Idea: objects of interest are not *points* of *X*, but *dipaths* in  $\vec{P}X$ 

- equip  $\vec{P}X$  with compact-open topology
- *PX* is standard topological space
  ⇒ can use tools!

Usually consider traces: dipaths modulo direparametrizations:  $\vec{T}X$ 

- if X is precubical, then  $\vec{P}X \simeq \vec{T}X$ 
  - $\simeq$  prod*simplicial* complex
  - $\simeq \operatorname{prod} permutahedral \operatorname{complex}$
  - $\simeq$  nerve of cube chain category



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## Directed Homology

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Natural Homolo	σν		

- - Trace space  $\vec{T}X$  forms a (topological) category: objects points; morphisms  $\vec{T}X(x, y)$  traces from x to y
  - Idea:  $\vec{H}_n X(x, y) = H_{n-1} \vec{T} X(x, y)$
  - These combine into a *natural system* of abelian groups:
  - Let  $\vec{FTX}$  be the factorization category of  $\vec{TX}$



- $\vec{H}_n$  maps traces  $\beta \in \vec{T}X(x, y)$  to  $H_{n-1}\vec{T}X(x, y)$
- and extensions  $(\alpha * * \gamma)$  to  $H_{n-1}(\alpha * * \gamma)$

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### Natural Homology

#### Huge but manageable:



Fig. 2: Natural homology of two simple pospaces

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Conclusion			

- Programs are directed topological spaces
  - $\bullet \ \mathsf{po-spaces} \hookrightarrow \mathsf{lpo-spaces} \hookrightarrow \mathsf{d-spaces}$
  - (Ipo-spaces  $\rightarrow$  po-spaces: delooping / universal dicover)
  - executions are dipaths; equivalence of executions is dihomotopy
- Programs are precubical sets
  - higher-dimensional automata
  - executions are tracks; equivalence of executions is track homotopy
  - strong link to spaces via geometric realization
- Invariants
  - fundamental category, component category
  - path spaces
  - natural homology

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### Current Work

- Languages of higher-dimensional automata
- Path spaces via cube chains and discrete Morse theory
- Model categories for directed topology
- Directed homology via persistent homology
- Higher-dimensional Kleene algebra

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